

Unsupervised Learning

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Unsupervised learning

Unsupervised learning

- ▶ in *supervised learning* we deal with pairs of records u, v
- ▶ goal is to predict v from u using a prediction model
- ▶ the output records v^i 'supervise' the learning of the model

- ▶ in *unsupervised learning*, we deal with only records u
- ▶ goal is to *build a data model* of u , in order to
 - ▶ *reveal structure* in u
 - ▶ *impute missing entries* (fields) in u
 - ▶ *detect anomalies*
- ▶ yes, the first goal is vague . . .

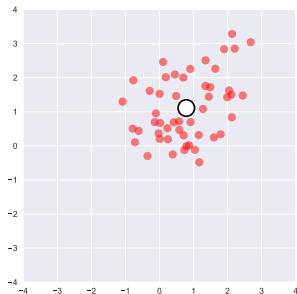
Embedding

- ▶ as usual we embed raw data u into a feature vector $x = \phi(u) \in \mathbf{R}^d$
- ▶ we then build a data model for the feature vectors
- ▶ we un-embed when needed, to go back to the raw vector u
- ▶ so we'll work with feature vectors from now on
- ▶ (embedded) data set has the form $x^1, \dots, x^n \in \mathbf{R}^d$

Data model

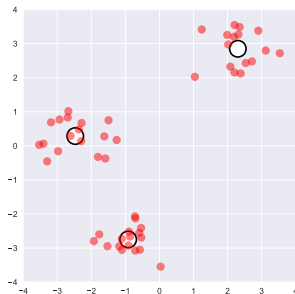
- ▶ a *data model* tells us what the vectors in some data set ‘look like’
- ▶ can be expressed quantitatively by an *implausibility function* or *loss function*
 $\ell : \mathbf{R}^d \rightarrow \mathbf{R}$
- ▶ $\ell(x)$ is how implausible x is as a data point
 - ▶ $\ell(x)$ small means x ‘looks like’ our data, or is ‘typical’
 - ▶ $\ell(x)$ large means x does not look like our data
- ▶ if our model is probabilistic, *i.e.*, x comes from a density $p(x)$, we can take $\ell(x) = -\log p(x)$, the *negative log density*
- ▶ other names for $\ell(x)$: surprise, perplexity, ...
- ▶ ℓ is often *parametrized* by a vector or matrix θ , and denoted $\ell_\theta(x)$

A simple constant model



- ▶ data model: x is near a fixed vector $\theta \in \mathbf{R}^d$
- ▶ $\theta \in \mathbf{R}^d$ parametrizes the model
- ▶ some implausibility functions:
 - ▶ $\ell_{\theta}(x) = \|x - \theta\|^2 = \sum_{i=1}^d (x_i - \theta_i)^2$ (square loss)
 - ▶ $\ell_{\theta}(x) = \|x - \theta\|_1 = \sum_{i=1}^d |x_i - \theta_i|$ (absolute loss)

K -means data model



- ▶ data model: x is close to one of the k representatives $\theta_1, \dots, \theta_k \in \mathbb{R}^d$
- ▶ quantitatively: for our data points x , the quantity

$$\ell_{\theta}(x) = \min_{i=1, \dots, k} \|x - \theta_i\|^2$$

i.e., the minimum distance squared to the representatives, is small

- ▶ $d \times k$ matrix $\theta = [\theta_1 \cdots \theta_k]$ parametrizes the k -means data model

Imputing missing entries

Imputing missing entries

- ▶ suppose x has some entries missing, denoted $?$ or NA or NaN
- ▶ $\mathcal{K} \subseteq \{1, \dots, d\}$ is the set of *known entries*
- ▶ we use our data model to guess or *impute* the missing entries
- ▶ we'll denote the imputed vector as \hat{x}
- ▶ $\hat{x}_i = x_i$ for $i \in \mathcal{K}$
- ▶ imputation example, with $\mathcal{K} = \{1, 3\}$

$$x = \begin{bmatrix} 12.1 \\ ? \\ -2.3 \\ ? \end{bmatrix} \implies \hat{x} = \begin{bmatrix} 12.1 \\ -1.5 \\ -2.3 \\ 3.4 \end{bmatrix}$$

- ▶ we are imputing or guessing $\hat{x}_2 = -1.5$, $\hat{x}_4 = 3.4$
- ▶ the other entries we know: $\hat{x}_1 = x_1 = 12.1$, $\hat{x}_3 = x_3 = -2.3$

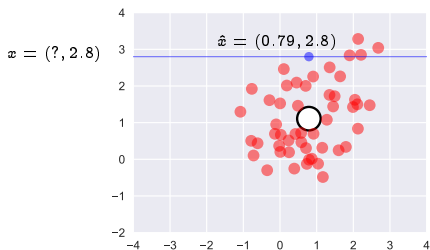
Imputation using a data model

- ▶ given partially specified vector x we minimize over the unknown entries:

$$\begin{aligned} & \text{minimize} && \ell_{\theta}(\hat{x}) \\ & \text{subject to} && \hat{x}_i = x_i, \quad i \in \mathcal{K} \end{aligned}$$

- ▶ *i.e.*, impute the unknown entries to minimize the implausibility, subject to the given known entries

Imputing with constant data model



- ▶ given x with some entries unknown
- ▶ constant data model with implausibility function $\ell_{\theta}(x) = \|x - \theta\|^2$
- ▶ we minimize $(\hat{x}_1 - \theta_1)^2 + \dots + (\hat{x}_d - \theta_d)^2$ subject to $\hat{x}_i = x_i$ for $i \in \mathcal{K}$
- ▶ so $\hat{x}_i = x_i$ for $i \in \mathcal{K}$
- ▶ for $i \notin \mathcal{K}$, we take $\hat{x}_i = \theta_i$
- ▶ i.e., for the unknown entries, guess the model parameter entries
- ▶ example has $\theta = (0.79, 1.11)$

Imputing with k -means data model

- ▶ given x with some entries unknown
- ▶ k -means data model with implausibility function
$$\ell_{\theta}(x) = \min_{i=1, \dots, k} \|x - \theta_i\|^2$$
- ▶ find nearest representative θ_j to x , using only known entries
- ▶ *i.e.*, find j that minimizes $\sum_{i \in \mathcal{K}} (x_i - (\theta_j)_i)^2$
- ▶ guess $\hat{x}_i = (\theta_j)_i$ for $i \notin \mathcal{K}$
- ▶ *i.e.*, for the unknown entries, guess the entries of the closest representative

Supervised learning as special case of imputation

- ▶ suppose we wish to predict $y \in \mathbf{R}$ based on $x \in \mathbf{R}^d$
- ▶ we have some training data $x^1, \dots, x^n, y^1, \dots, y^n$
- ▶ define $(d + 1)$ -vector $\tilde{x} = (x, y)$

- ▶ build data model for \tilde{x} using training data $\tilde{x}^1, \dots, \tilde{x}^n$
- ▶ to predict y given x , impute last entry of $\tilde{x} = (x, ?)$

Validating imputation

we can validate a proposed data model (and imputation method):

- ▶ divide data into a training and a test set
- ▶ build data model on the training set
- ▶ mask some entries in the vectors in the test set (*i.e.*, replace them with ?)
- ▶ impute these entries and evaluate the average error or loss of the imputed values, *e.g.*, the RMSE

Fitting data models

Generic fitting method

- ▶ given data x^1, \dots, x^n (with no missing entries), and parametrized implausibility function $\ell_\theta(x)$
- ▶ how do we choose the parameter θ ?
- ▶ average implausibility or *empirical loss* is

$$\mathcal{L}(\theta) = \frac{1}{n} \sum_{i=1}^n \ell_\theta(x^i)$$

- ▶ choose θ to minimize $\mathcal{L}(\theta)$, (possibly) subject to $\theta \in \Theta$, the set of acceptable parameters
- ▶ *i.e.*, choose parameter θ so the observed data is least implausible

Fitting a constant model with sum squares loss

- ▶ sum squares implausibility function $\ell_{\theta}(x) = \|x - \theta\|^2$
- ▶ empirical loss is

$$\mathcal{L}(\theta) = \frac{1}{n} \sum_{i=1}^n \|x^i - \theta\|^2$$

- ▶ minimizing over θ yields

$$\theta = \frac{1}{n} \sum_{i=1}^n x^i$$

the mean of the data vectors

Fitting a constant model with sum absolute loss

- ▶ sum absolute implausibility function $\ell_{\theta}(x) = \|x - \theta\|_1$
- ▶ empirical loss is

$$\mathcal{L}(\theta) = \frac{1}{n} \sum_{i=1}^n \|x^i - \theta\|_1$$

- ▶ minimizing over θ yields

$$\theta = \text{median}(x^1, \dots, x^n)$$

the elementwise median of the data vectors

Fitting a k -means model

- ▶ implausibility function $\ell_{\theta}(\mathbf{x}) = \min_{j=1, \dots, k} \|\mathbf{x} - \theta_j\|^2$
- ▶ parameter is $d \times k$ matrix with columns $\theta_1, \dots, \theta_k$
- ▶ empirical loss is

$$\mathcal{L}(\theta) = \frac{1}{n} \sum_{i=1}^n \min_{j=1, \dots, k} \|\mathbf{x}^i - \theta_j\|^2$$

- ▶ this is the k -means objective function!
- ▶ we can use the k -means algorithm to (approximately) minimize $\mathcal{L}(\theta)$, i.e., fit a k -means model

K-means algorithm

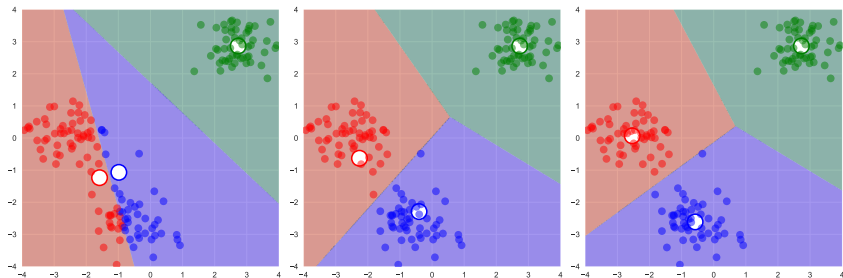
- ▶ define the *assignment* or *clustering* vector $c \in \mathbf{R}^n$
- ▶ c_i is the cluster that data vector x^i is in (so $c_i \in \{1, \dots, k\}$)
- ▶ to minimize

$$\mathcal{L}(\theta) = \frac{1}{n} \sum_{i=1}^n \min_{j=1, \dots, k} \|x^i - \theta_j\|^2$$

we minimize $\frac{1}{n} \sum_{i=1}^n \|x^i - \theta_{c_i}\|^2$ over both c and $\theta_1, \dots, \theta_k$

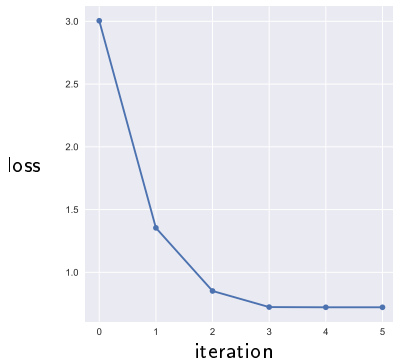
- ▶ we can minimize over c using $c_i = \operatorname{argmin}_j \|x^i - \theta_j\|^2$
- ▶ we can minimize over $\theta_1, \dots, \theta_k$ using θ_i as the average of $\{x^j \mid c_j = i\}$
- ▶ *k*-means algorithm alternates between these two steps
- ▶ it is a heuristic for (approximately) minimizing $\mathcal{L}(\theta)$

K -means example



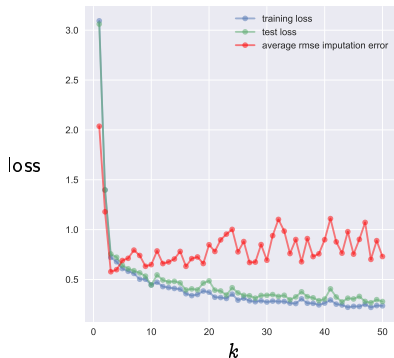
► 200 data points; reserve 40 for test

K -means example



- convergence after 4 iterations

K -means example



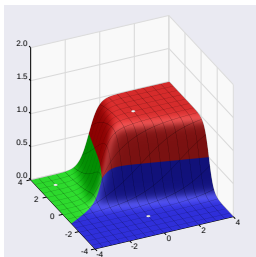
- ▶ fit k -mean data model for $k = 1, 2, \dots, 50$
- ▶ validate by removing randomly either u_1 or u_2 from each record in test set

Revealing structure in data

Structure from a data model

- ▶ a data model can reveal structure of the data
- ▶ can be used for other purposes, some of them vague
- ▶ a good k -means model suggests that data come from k different 'modes' or 'regimes' or 'processes'
- ▶ examples:
 - ▶ partition 5 sec mobile phone accelerometer data into different patterns (walking, sitting, running, biking, *etc.*)
 - ▶ partition customer purchase data into market segments
 - ▶ partition articles into different topics, authors

Features from a data model



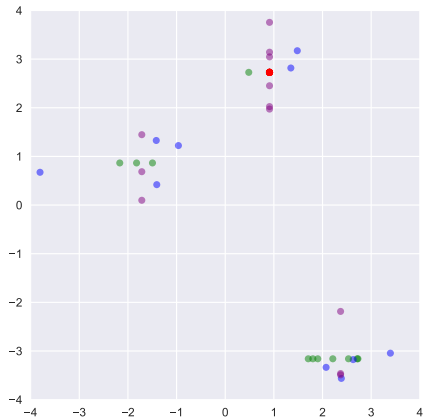
- ▶ we can use a k -means data model to generate new features
- ▶ one-hot: map x to $\tilde{x} = e_i$, $i = \operatorname{argmin}_j \|x - \theta_j\|^2$
- ▶ soft version: map x to $\tilde{x} \in \mathbf{R}^k$, ($\sigma > 0$ is a hyper-parameter)

$$\tilde{x}_i = \frac{e^{-\|x - \theta_i\|^2 / \sigma^2}}{e^{-\|x - \theta_1\|^2 / \sigma^2} + \dots + e^{-\|x - \theta_k\|^2 / \sigma^2}}, \quad i = 1, \dots, k$$

Missing entries in a data set

- ▶ we've so far assumed that there are no missing entries in the data set used to build the data model
- ▶ let's see how to handle the case when entries are missing
- ▶ first, standardize data using known entries
- ▶ replace missing entries with zeros
- ▶ build data model
- ▶ use data model to impute missing entries
- ▶ now build new data model, and repeat

Example: Missing entries in a data set



- ▶ blue points known, purple points have missing x coordinate, green points missing y coordinate, red points missing both

Recommendation system

- ▶ features are movies; examples are customer ratings
- ▶ entries are either rating (say, between 1 and 5) or *?* if the customer did not rate that movie
- ▶ imputed entries are our guess of *what rating the customer would give, if they rated that movie*
- ▶ we can *recommend* movies to a customer for which the imputed entry is large